

# Advanced imaging techniques

Sarrvesh S. Sridhar

ASTRON

June 28, 2018

## Recap: Imaging

- From the lecture, we saw

$$I_{\text{True}}(l, m) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} V_{\text{True}}(u, v) e^{i2\pi(u l + v m)} du dv \quad (1)$$

## Recap: Imaging

- From the lecture, we saw

$$I_{\text{True}}(l, m) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} V_{\text{True}}(u, v) e^{i2\pi(u l + v m)} du dv \quad (1)$$

- But, we do not measure  $V(u, v)$  for all values of  $u$  and  $v$ .

## Recap: Imaging

- From the lecture, we saw

$$I_{\text{True}}(l, m) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} V_{\text{True}}(u, v) e^{i2\pi(u l + v m)} du dv \quad (1)$$

- But, we do not measure  $V(u, v)$  for all values of  $u$  and  $v$ .
- So, we define a window function  $W(u, v)$

$$I_{\text{Obs}}(l, m) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} W(u, v) V_{\text{True}}(u, v) e^{i2\pi(u l + v m)} du dv \quad (2)$$

## Recap: Imaging

- From the lecture, we saw

$$I_{\text{True}}(l, m) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} V_{\text{True}}(u, v) e^{i2\pi(u l + v m)} du dv \quad (1)$$

- But, we do not measure  $V(u, v)$  for all values of  $u$  and  $v$ .
- So, we define a window function  $W(u, v)$

$$I_{\text{Obs}}(l, m) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} W(u, v) V_{\text{True}}(u, v) e^{i2\pi(u l + v m)} du dv \quad (2)$$

$$I_{\text{Obs}}(l, m) = \mathcal{F}^{-1}[W(u, v) V(u, v)] \quad (3)$$

## Recap: Imaging

- From the lecture, we saw

$$I_{\text{True}}(l, m) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} V_{\text{True}}(u, v) e^{i2\pi(u l + v m)} du dv \quad (1)$$

- But, we do not measure  $V(u, v)$  for all values of  $u$  and  $v$ .
- So, we define a window function  $W(u, v)$

$$I_{\text{Obs}}(l, m) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} W(u, v) V_{\text{True}}(u, v) e^{i2\pi(u l + v m)} du dv \quad (2)$$

$$I_{\text{Obs}}(l, m) = \mathcal{F}^{-1}[W(u, v) V(u, v)] \quad (3)$$

$$I_{\text{Obs}}(l, m) = \mathcal{F}^{-1}[W(u, v)] * \mathcal{F}^{-1}[V(u, v)] \quad (4)$$

## Deconvolution

- From the previous slide,

$$I_{\text{Obs}}(l, m) = \mathcal{F}^{-1}[W(u, v)] \circledast \mathcal{F}^{-1}[V(u, v)] \quad (5)$$

- ▶  $\mathcal{F}^{-1}[W(u, v)]$  is called “dirty beam”
- ▶  $I_{\text{Obs}}(l, m)$  is called the “dirty image”
- ▶  $\mathcal{F}^{-1}[V(u, v)]$  is the “true sky”
- The “dirty image” is the “true sky” convolved by the “dirty beam”.
- To get the “true” sky image → we deconvolve our “dirty image” with the “dirty beam”

## Non co-planar baselines

- The 2D Fourier transform assumes a small field of view.

$$I_{\text{True}}(l, m) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} V_{\text{True}}(u, v) e^{i2\pi(u l + v m)} du dv \quad (6)$$

## Non co-planar baselines

- The 2D Fourier transform assumes a small field of view.

$$I_{\text{True}}(l, m) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} V_{\text{True}}(u, v) e^{i2\pi(u l + v m)} du dv \quad (6)$$

- In its full glory,  $V_{\text{True}}$  and  $I_{\text{True}}$  are related as

$$V_{\text{True}}(u, v, w) = \int \int \frac{I_{\text{True}}(l, m)}{\sqrt{1 - l^2 - m^2}} e^{-i2\pi(u l + v m + w(\sqrt{1 - l^2 - m^2} - 1))} dl dm \quad (7)$$

- $V_{\text{True}}$  and  $I_{\text{True}}$  do not form a Fourier transform pair!

# Non co-planar baselines

- Two solutions:

## ① Facetting

- ★ Split the sky into sub-images (or facets)
- ★ Small field approximation holds in each facet
- ★ Fourier pair in each facet
- ★ In CASA **clean**, use **gridmode='widefield'**, **facets=N**

# Non co-planar baselines

- Two solutions:

## ① Facetting

- ★ Split the sky into sub-images (or facets)
- ★ Small field approximation holds in each facet
- ★ Fourier pair in each facet
- ★ In CASA **clean**, use **gridmode='widefield'**, **facets=N**

## ② W-projection

- ★ Commonly used solution.
- ★ See Cornwell et al (2011)
- ★ In CASA **clean**, use **gridmode='widefield'**, **wprojplanes=-1**

$$V_{\text{True}}(u, v, w) * e^{-i2\pi w(\sqrt{1-l^2-m^2}-1)} = \int \int \frac{I_{\text{True}}(l, m)}{\sqrt{1 - l^2 - m^2}} e^{-i2\pi(u l + v m)} dl dm \quad (8)$$

# W-projection

- Near the pointing center → no noticeable difference.

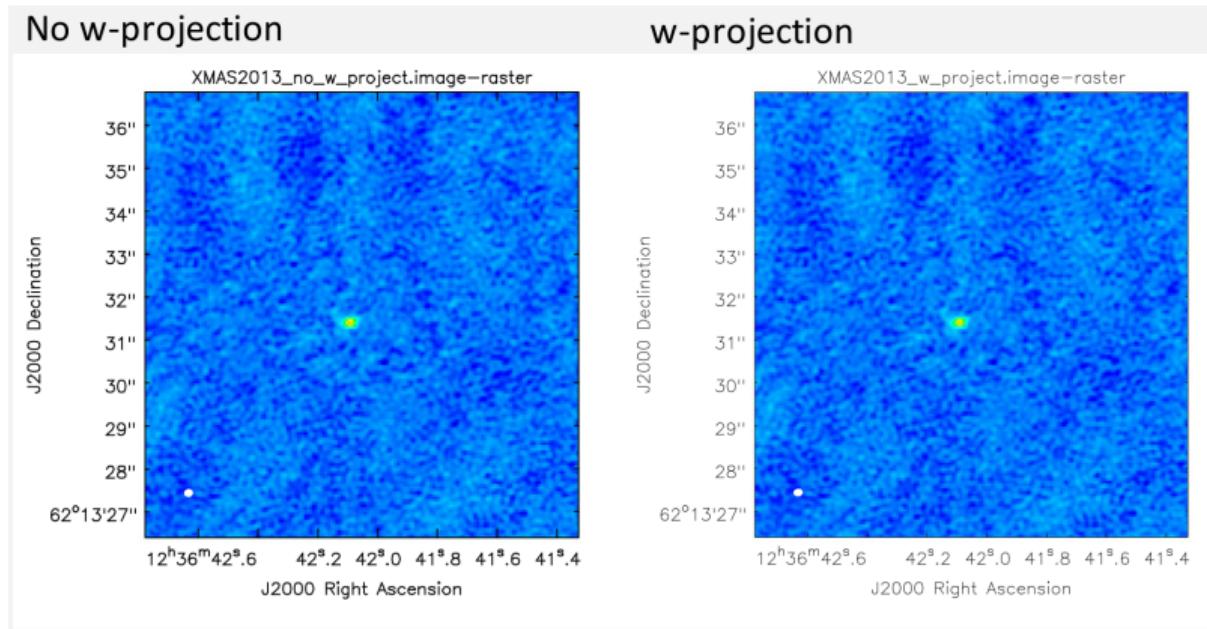


Image credit: Jack Radcliffe

# W-projection

- Away from the pointing center.

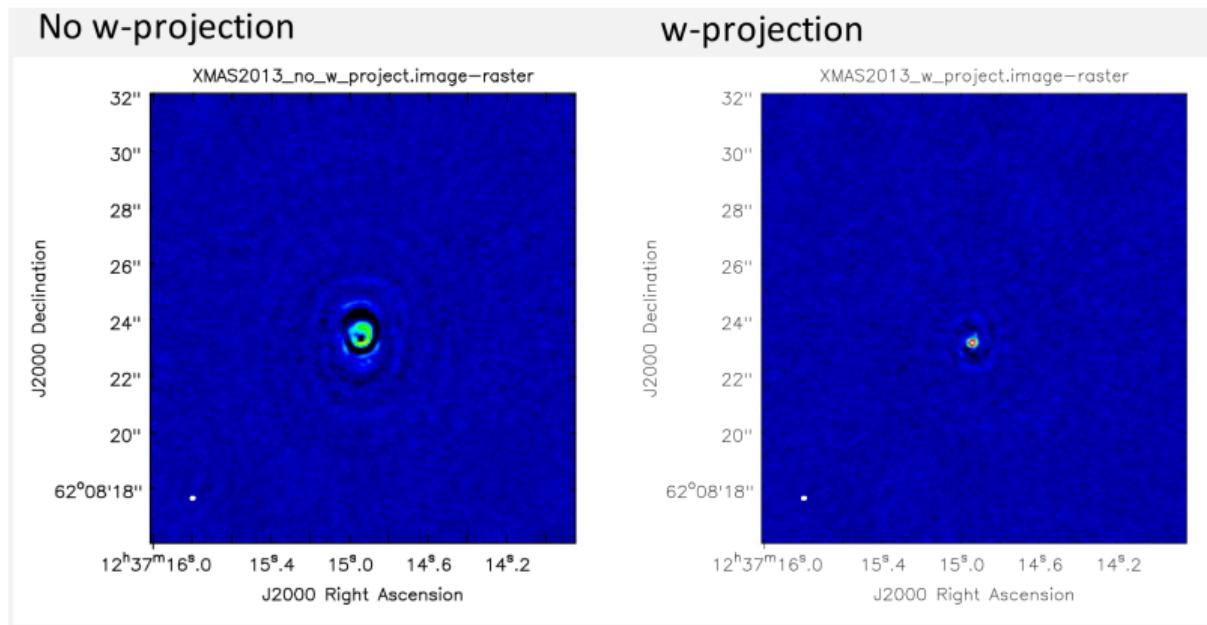


Image credit: Jack Radcliffe

# Multi-scale CLEAN

- Classic CLEAN → collection of delta functions.

# Multi-scale CLEAN

- Classic CLEAN → collection of delta functions.
- Multi-scale CLEAN → collection of (Gaussian) kernels with different scales.

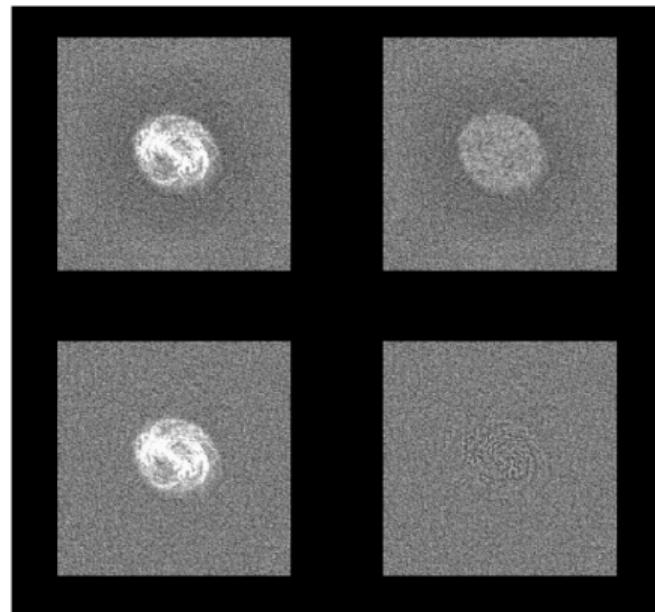


Image: Cornwell (2008)

## Multi-scale CLEAN

- In CASA **clean()**, for example use “multiscale=[0,1,5,15]”.

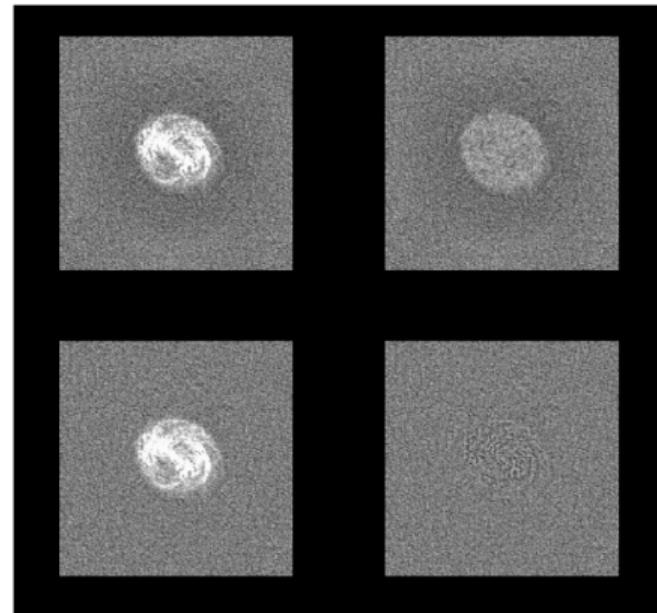


Image: Cornwell (2008)

## Wideband deconvolution

- CLEAN does not account for spectral variations within the band.

## Wideband deconvolution

- CLEAN does not account for spectral variations within the band.

**See demonstration**

## Other advanced techniques

- Direction-dependent calibration – See science talk.
- W-stacking
- Auto-masking & auto-thresholding – Offringa & Smirnov (2017)
- A-projection
- Compressed sensing
- ...